

# Week 8

## Dynamic Programming

- 1 Introduction
- 2 Making change
- 3 A general framework
- 4 Matrix chain multiplication
- 5 Longest common subsequence
- 6 Floyd-Warshall algorithm

## Read:

- CLRS Chapter 15.
- We cover Section 15.2, 15.3, 15.4.
- Section 15.1 is a nice introduction, so it would be good if you could also read this.
- We also treat Section 25.2.

You might consider appendix

### D.1 “Matrices and matrix operations”

The first example (change-making) is considered in detail, while the other three examples are handled more quickly —

the point here is to understand the principle  
of “dynamic programming”.

# When greedy algorithms fail: making change

Suppose we want to solve the Making Change problem of paying 9 pence with 1, 4 and 6 pence coins.

- The greedy algorithm gives  $6+1+1+1$  rather than the optimal  $4+4+1$ .
- So a new idea is required.
- We need a more systematic way of searching for a solution.
- While we want to avoid (if possible) searching through all possible combinations.

Perhaps we can solve very simple problems, and then proceed recursively:

- 1 If 0 pence is to be returned, we just use zero coins (whatever the coins are).
- 2 If we just have one coin, then the solution is also clear.

## Dealing with two coins

Now assume that we have two coins with values  $d_1 \neq d_2$ , and we have to pay the sum of  $N$  pence. Consider an optimal solution  $a_1 \cdot d_1 + a_2 \cdot d_2$  (assuming a solution exists at all!), using  $a_1 + a_2$  coins.

- 1 Either we use coin  $d_2$  or not.
- 2 That is, either  $a_2 > 0$  or  $a_2 = 0$ .
- 3 In the second case, only one coin is left and we are done.
- 4 So *assume*  $a_2 > 0$ .
- 5 We know  $d_2$  is used at least once.
- 6 Now for the amount  $N - d_2$  we know that  $a_1 \cdot d_1 + (a_2 - 1) \cdot d_2$  is an optimal solution!
- 7 Since if there would be a solution using fewer coins, then by using one more coin we would obtain a better solution for the original problem.

# Making change: the general idea

We arrive at the idea of a general strategy, to solve the problem with coins  $d_1, \dots, d_n$  and amount  $N$  to be payed:

- Look how we do if we use only coins  $d_1, \dots, d_{n-1}$ .
- Look how we do if we use  $d_n$  once, decreasing  $N$  to  $n - d_n$ .
- Compare the two possibilities, and choose the better.

This scheme is to be applied recursively.

# Making change: the general structure

So we can solve the general Making Change problem as follows:

- In order to pay the sum of  $N$  pence using  $n$  distinct coins  $(d_1, d_2, \dots, d_n)$ ,  
we set up an  $n \times (N+1)$  table  $c[1 \dots n, 0 \dots N]$ .
- In this table,  $c[i, j]$  will hold the minimum number of coins required to pay the amount  $j$  using only coins  $d_1, \dots, d_i$ .  
*(If no arrangement of such coins makes up  $j$  pence, then we shall have  $c[i, j] = \infty$ .)*
- The solution will then be contained in  $c[n, N]$ .

The table is filled out recursively according to the case-distinction “use last coin or not”.

# Bookkeeping for making change

To summarise we fill out the table as follows:

- Clearly  $c[i, 0] = 0$  for every  $i$ .
- Also, for every  $j$ ,  $c[1, j] = \begin{cases} j \operatorname{div} d_1 & \text{if } j \bmod d_1 = 0, \\ \infty & \text{otherwise.} \end{cases}$   
(Whenever we cannot make change for amount  $j$  using coins  $d_1, \dots, d_i$ , we let  $c[i, j] = \infty$ .)
- For  $c[i, j]$  ( $i > 1, j > 0$ ), we either:
  - pay  $j$  pence using only coins  $d_1, \dots, d_{i-1}$ :  $c[i, j] \leq c[i-1, j]$
  - or use (at least) one coin  $d_i$ , and reduce the problem to that of paying  $j-d_i$ :  $c[i, j] \leq 1 + c[i, j-d_i]$ .
- As we want to minimise the number of coins, we choose the better of these two options:

$$c[i, j] = \min (c[i-1, j], 1 + c[i, j-d_i]).$$

# The making-change algorithm

MAKING-CHANGE( $N, d[1..n]$ )

//Running time  $O(nN)$

```
1  for  $i = 1$  to  $n$ 
2       $c[i, 0] = 0$ 
3  for  $j = 1$  to  $N$ 
4      if  $(j \bmod d_1) = 0$ 
5           $c[1, j] = j \operatorname{div} d_1$ 
6      else  $c[1, j] = \infty$ 
7  for  $i = 2$  to  $n$ 
8      for  $j = 1$  to  $N$ 
9          if  $j < d_i$ 
10              $c[i, j] = c[i-1, j]$ 
11         else  $c[i, j] = \min(c[i-1, j], 1 + c[i, j-d_i])$ 
12 return  $c$ 
```

# The making-change algorithm (continued)

**Example:** Paying 9 pence using 6, 1 and 4 pence coins (order irrelevant).

<i>Amount</i>	0	1	2	3	4	5	6	7	8	9
$d_1 = 6$	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	1	$\infty$	$\infty$	$\infty$
$d_2 = 1$	<span style="border: 1px solid black;">0</span>	<span style="border: 1px solid black;">1</span>	2	3	4	5	1	2	3	4
$d_3 = 4$	0	<span style="border: 1px solid black;">1</span>	2	3	1	<span style="border: 1px solid black;">2</span>	1	2	2	<span style="border: 1px solid black;">3</span>

## Determining an optimal solution

The algorithm MAKING-CHANGE tells us that  $c[3, 9] = 3$  coins are sufficient to make up 9 pence – but *which* three coins to use?

The following algorithm will answer that, retracing the solution through the  $c$ -table (precomputed by MAKING-CHANGE). The output is an array  $a_1, \dots, a_n$  of natural numbers  $\geq 0$  such that

$$a_1 \cdot d_1 + \dots + a_n \cdot d_n = N$$

and such that  $a_1 + \dots + a_n$  is minimal.

PAY-OUT( $c[1..n, 0..N], d[1..n]$ )

```
1  for ( $i = 1; i \leq n; ++i$ )  $a[i] = 0$ ;  
2   $i = n; j = N$ ;  
3  while  $j > 0$   
4      if ( $i = 1$ )  $a[1] = c[1][j]; j = 0$   
5      else if ( $c[i, j] = c[i - 1, j]$ )  $i = i - 1$   
6      else  $a[i] = a[i] + 1; j = j - d_i$   
7  return  $a$ 
```

# Complexity of finding an optimal solution

- This algorithm involves stepping back (at most)  $n$  rows, and making  $c[n, N]$  jumps to the left.
- Hence it runs in time  $O(n + N)$ .
- Thus it is a negligible addition to the  $O(nN)$  algorithm `MAKING-CHANGE`.

Of course, we could have computed the array  $a_1, \dots, a_n$  right away directly in `MAKING-CHANGE` — we don't need array  $c$  to be completely computed. As an exercise, modify the code of `MAKING-CHANGE` to do so.

# Why the greedy algorithm fails

As with problems which can be solved by greedy algorithms, MAKING-CHANGE has the

**Optimal Substructure Property:** An optimal solution to the problem contains optimal solutions to subproblems.

However, the *greedy-choice property* fails. We now have to consider many potential solutions, which requires added bookkeeping: we need to remember past decisions, and also build solutions from the bottom up.

We do have something though, namely the

**Overlapping Subproblems Property:** The space of subproblems is small, so an otherwise-obvious top-down, divide-and-conquer recursive algorithm would solve the same subproblems *over and over*.

# Dynamic programming

The presence of

- **Optimal Substructure Property** and
- **Overlapping Subproblems Property**

characterises **Dynamic Programming**.

With dynamic programming, we take a natural recursive definition, and instead of computing it in a *top-down* fashion, we compute it *bottom-up*, exploiting the **overlapping subproblems property** by only solving each subproblem once.

For example, a top-down algorithm for computing Fibonacci numbers from their definition:

$$F_0 = 0 \quad F_1 = 1 \quad F_n = F_{n-1} + F_{n-2}$$

would run in exponential time, while a bottom-up algorithm, computing  $F_0, F_1, F_2, F_3, F_4, \dots, F_{n-1}, F_n$  would run in linear time.

# Matrix chain multiplication

**Assumption:** Computing  $A \cdot B$ , where  $A$  is a  $p \times q$  matrix and  $B$  is a  $q \times r$  matrix, requires  $p \cdot q \cdot r$  scalar multiplications.

**Question:** What is the most efficient order for multiplying  $A_1 \cdot A_2 \cdot \dots \cdot A_n$  where  $A_i$  is a  $p_{i-1} \times p_i$  matrix?

**Example:**  $A_1, A_2, A_3, A_4$  are matrices of dimensions  $6 \times 2, 2 \times 5, 5 \times 4, 4 \times 3$ . Then  $A_1 A_2 A_3 A_4$  can be computed in five ways:

$$((A_1 A_2) A_3) A_4 \rightsquigarrow 252 \text{ scalar multiplications}$$

$$(A_1 A_2)(A_3 A_4) \rightsquigarrow 210 \text{ scalar multiplications}$$

$$(A_1(A_2 A_3)) A_4 \rightsquigarrow 160 \text{ scalar multiplications}$$

$$A_1((A_2 A_3) A_4) \rightsquigarrow 100 \text{ scalar multiplications}$$

$$A_1(A_2(A_3 A_4)) \rightsquigarrow 126 \text{ scalar multiplications.}$$

So the right choice can make a big difference. But we would like to avoid making this choice by exhaustive search as in the above example, since there are exponentially many possibilities (in the number of matrices).

# Example explained

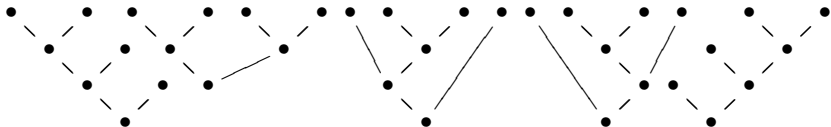
Why does the computation of  $((A_1A_2)A_3)A_4$  need 252 scalar multiplications?

- 1  $B := A_1A_2$ :  $6 \times 2$ ,  $2 \times 5$  matrices, needs  $6 \cdot 2 \cdot 5 = 60$  multiplications, yields  $6 \times 5$  matrix.
- 2  $C := BA_3$ :  $6 \times 5$ ,  $5 \times 4$  matrices, needs  $6 \cdot 5 \cdot 4 = 120$  multiplications, yields  $6 \times 4$  matrix.
- 3  $CA_4$ :  $6 \times 4$ ,  $4 \times 3$  matrices, needs  $6 \cdot 4 \cdot 3 = 72$  multiplications;

So altogether  $60 + 120 + 72 = 252$  multiplications are needed.

# How many possibilities are there?

The possibilities to multiply  $n$  matrices correspond exactly to the (unlabelled!) ordered rooted trees with  $n$  leaves, where every non-leaf node has exactly two children:



The number of such rooted trees is

$$\frac{\binom{2n-2}{n-1}}{n}$$

so for  $n = 4$  we get  $\binom{6}{3}/4 = 5$ . In general this number grows exponentially.

## The key observation

- If  $n = 1$  then the problem is trivial (nothing to multiply). Also for  $n = 2$  it's trivial, but we don't need that.
- Now regarding the product  $A_1 \cdot \dots \cdot A_n$ ,  $n \geq 2$ : In the tree of operations we consider the root. It has two children, representing a partitioning of  $\{1, \dots, n\}$  into two intervals.
- So the point is to choose  $1 \leq k < n$ , and to compute  $B := A_1 \cdot \dots \cdot A_k$  and  $C := A_{k+1} \cdot \dots \cdot A_n$  optimally.
- When choosing  $k$ , for its evaluation we have to add up the costs for the two subcalculations of  $B$  and  $C$  plus the cost for the single computation of  $B \cdot C$ .
- Optimality is obvious.

So here we just have a one-dimensional recursive descent (while for change-making it was two-dimensional).

*Note: A prerequisite for dynamic programming is the ability to precisely calculate the cost of what is to be optimised.*

## A dynamic programming solution

Let  $m[i, j]$  be the cost (number of scalar multiplications) of computing  $A_i \times A_{i+1} \times \cdots \times A_j$  using an optimal order of multiplying the matrices. Then

$$m[i, j] = \begin{cases} 0 & \text{if } i = j, \\ \min_{i \leq k < j} (m[i, k] + m[k + 1, j] + p_{i-1}p_kp_j) & \text{if } i < j. \end{cases}$$

- If we implement this as a top-down recursive algorithm, it would run in exponential time (since again we have two recursive calls, where the size of the subproblems is only slightly decreased).
- However, there are only a quadratic number of subproblems!
- The recursive algorithm solves these over and over.
- So we use a bottom-up dynamic-programming algorithm.

# Again: how to get the (full) solution?

- $m[1, n]$  only tells us how many scalar multiplications are necessary in the optimal solution, not what the optimal solution is (i.e., the order in which to multiply the matrices).
- For this, we can maintain a second table  $s$ , and record in  $s[i, j]$  the value of  $k$  from which the minimal value of  $m[i, j]$  was computed.

# The algorithm

MATRIX-CHAIN-ORDER( $p$ )

//Running time  $O(n^3)$

```

1   $n = \text{length}(p) - 1$ 
2  for  $i = 1$  to  $n$ 
3       $m[i, i] = 0$ 
4  for  $l = 2$  to  $n$ 
5      for  $i = 1$  to  $n - l + 1$ 
6           $j = i + l - 1; m[i, j] = \infty$ 
7          for  $k = i$  to  $j - 1$ 
8               $q = m[i, k] + m[k + 1, j] + p_{i-1}p_kp_j$ 
9              if  $q < m[i, j]$ 
10                  $m[i, j] = q; s[i, j] = k$ 
11 return  $(m, s)$ 

```

Variable  $l$  is the “span”, that is, how many matrices are involved in the current consideration:

- 1 The initialisation corresponds to  $l = 1$ .
- 2 The still trivial case of  $l = 2$  is then considered.
- 3 Then  $l = 3$ , and so on.

## Running the example

For our example,  $p = (6, 2, 5, 4, 3)$ , and the tables computed are:

$m$	1	2	3	4
1	0	60	88	100
2	—	0	40	64
3	—	—	0	60
4	—	—	—	0

$s$	1	2	3	4
1	0	1	1	1
2	—	0	2	3
3	—	—	0	3
4	—	—	—	0

So we obtain  $A_1((A_2A_3)A_4)$  (with 100 multiplications) as optimal solution.

Note that peculiar way how we run through the  $m$ -array:

- 1 First  $l = 1$ , that is, setting the diagonal to zero.
- 2 Then  $l = 2$ , considering all pairs  $(1, 2), (2, 3), \dots$ , and setting them to their directly given value.
- 3 Then  $l = 3$ , considering all pairs  $(1, 3), (2, 4), \dots$ , where now for the cuts (given by  $k$ ) all computations are already present. And so on.

## Printing the matrix-chain

Using the  $s$ -table, we can then reconstruct and print out an optimal Matrix Chain as follows (using  $s$  as computed by MATRIX-CHAIN-ORDER):

MATRIX-CHAIN-PRINT( $i, j$ )

```
1  if  $i = j$ 
2      print "A";
3  else print "("
4      MATRIX-CHAIN-PRINT( $i, s[i, j]$ )
5      MATRIX-CHAIN-PRINT( $s[i, j] + 1, j$ )
6      print ")"
```

We would then invoke this algorithm initially by

MATRIX-CHAIN-PRINT( $1, n$ ).

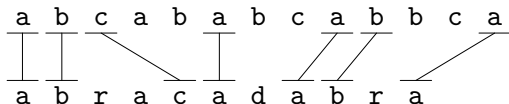
For our example, we get the output:  $(A_1((A_2A_3)A_4))$ .

- Alternatively, as before, instead of the post-processing we could also just modify MATRIX-CHAIN-ORDER to record the optimal steps found during the process of their computation.
- If we use another algorithm for multiplying two matrices, like Strassen's algorithm (as seen in week 3), then we just need to replace the term " $p_{i-1} \cdot p_k \cdot p_j$ " in the minimisation-equation with another (appropriate) term.
- Though this would need precise calculations (not just some big-Oh estimation).

# Longest common subsequence (LCS)

**Problem:** Given two sequences  $X = (x_1, x_2, \dots, x_m)$  and  $Y = (y_1, y_2, \dots, y_n)$ , find the longest common subsequence.

**Example:** The longest common subsequence of the sequences



is abcaaba and is of length 7.

There are  $2^m$  subsequences of  $X$ , so we would like avoiding to check them all with  $Y$ .

Fortunately, we can express this as a dynamic programming problem, and derive an efficient algorithm to solve it.

# Dynamic programming LCS

Let  $c[i, j]$  denote the length of the LCS of  $x_1 \dots x_i$  and  $y_1 \dots y_j$ .

Then  $c[m, n]$  is the length of the LCS we are trying to compute.

A recursive definition for  $c$ , exploiting an obvious optimal subproblem property, is given as follows.

$$c[i, j] = \begin{cases} 0 & \text{if } i = 0 \text{ or } j = 0, \\ c[i - 1, j - 1] + 1 & \text{if } i, j > 0 \text{ and } x_i = y_j, \\ \max(c[i, j - 1], c[i - 1, j]) & \text{if } i, j > 0 \text{ and } x_i \neq y_j. \end{cases}$$

# Computing the length of the LCS

The following is a dynamic-programming algorithm which computes  $c[i, j]$ , as well as a further table  $b[i, j]$  to use for constructing the LCS.

LCS-LENGTH( $X, Y$ ) //Running time  $O(mn)$

```

1   $m = \text{length}(X)$  ;   $n = \text{length}(Y)$ 
2  for  $i = 0$  to  $m$ 
3       $c[i, 0] = 0$ 
4  for  $j = 0$  to  $n$ 
5       $c[0, j] = 0$ 
6  for  $i = 1$  to  $m$ 
7      for  $j = 1$  to  $n$ 
8          if  $x_i = y_j$ 
9               $c[i, j] = c[i-1, j-1] + 1$  ;   $b[i, j] = "\diagdown"$ 
10             else if  $c[i-1, j] \geq c[i, j-1]$ 
11                  $c[i, j] = c[i-1, j]$  ;   $b[i, j] = "\uparrow"$ 
12             else  $c[i, j] = c[i, j-1]$  ;   $b[i, j] = "\leftarrow"$ 
13  return  $(c, b)$ 

```

# Printing the LCS

```
PRINT-LCS( $b, X, i, j$ ) //Running time  $O(m + n)$ 
1  if  $i=0$  or  $j=0$ 
2      return
3  else if  $b[i, j] = \uparrow$ 
4      PRINT-LCS( $b, X, i-1, j$ )
5  else if  $b[i, j] = \leftarrow$ 
6      PRINT-LCS( $b, X, i, j-1$ )
7  else PRINT-LCS( $b, X, i-1, j-1$ ); print  $x_i$ 
```

Note the motivation for the arrow-labels:

- 1  $\uparrow$  means to go one row up (same column).
- 2  $\leftarrow$  means go one column left (same row).
- 3  $\swarrow$  means to one row up and one column left.

## Example

LCS = BCBA

	$j$	0	1	2	3	4	5	6	7	8
$i$	$y_j$	<b>B</b>	D	<b>C</b>	B	B	A	<b>B</b>	<b>A</b>	
0	$x_i$	0	0	0	0	0	0	0	0	0
1	<b>A</b>	<b>0</b>	↑0	↑0	↑0	↑0	↑0	↖1	←1	↖1
2	<b>B</b>	0	↖1	←1	←1	↖1	↖1	↑1	↖2	←2
3	<b>C</b>	0	↑1	↑1	↖2	←2	←2	←2	↑2	↑2
4	<b>B</b>	0	↖1	↑1	↑2	↖3	↖3	←3	↖3	←3
5	<b>D</b>	0	↑1	↖2	↑2	↑3	↑3	↑3	↑3	↑3
6	<b>A</b>	0	↑1	↑2	↑2	↑3	↑3	↖4	←4	↖4

Note how to reconstruct the solution:

- 1 Start in the bottom-right corner, and follow the directed graph given by the arrows.
- 2 For fields marked by “↖” read off the corresponding letter.

# All-pairs shortest paths

**Problem:** Calculating the shortest route between any two cities from a given set of cities  $1, 2, \dots, n$ .

**Input:** A matrix  $d_{i,j}$  ( $1 \leq i, j \leq n$ ) of nonnegative values indicating the length of the direct route from  $i$  to  $j$ .

Note:  $d_{i,i} = 0$  for all  $i$ ; and if there is no direct route from  $i$  to  $j$ , then  $d_{i,j} = \infty$ .

**Output:** A shortest distance matrix  $s_{i,j}$  indicating the length of the shortest route from  $i$  to  $j$ .

We shall give a recursive definition for  $s$ , which can be computed by a dynamic-programming algorithm.

# The Floyd-Warshall algorithm

Let  $s_{i,j}^{(k)}$  denote the shortest distance from  $i$  to  $j$  which only passes through cities  $1, 2, \dots, k$  (besides  $i, j$ ). A recursive definition for  $s_{i,j}^{(k)}$  is given as follows.

$$s_{i,j}^{(k)} = \begin{cases} d_{i,j} & \text{if } k = 0, \\ \min \left( s_{i,j}^{(k-1)}, s_{i,k}^{(k-1)} + s_{k,j}^{(k-1)} \right) & \text{if } k > 0. \end{cases}$$

FLOYD-WARSHALL-1( $d, n$ )

```

1   $s^{(0)} = d$ 
2  for  $k = 1$  to  $n$ 
3      for  $i = 1$  to  $n$ 
4          for  $j = 1$  to  $n$ 
5               $s_{i,j}^{(k)} = \min \left( s_{i,j}^{(k-1)}, s_{i,k}^{(k-1)} + s_{k,j}^{(k-1)} \right)$ 
```

This algorithm runs in  $O(n^3)$  time and space. However, we can safely remove the superscripts from  $s$  (can you see why?), and achieve  $O(n^2)$  space.

## Constructing shortest paths

To construct the shortest paths, we maintain a *predecessor matrix*  $\pi_{i,j}$  in which  $\pi_{i,j}$  denotes the predecessor of  $j$  on some shortest path from  $i$  to  $j$ . (If  $i = j$  or there is no such path, then  $\pi_{i,j} = \text{NIL}$ .) The final algorithm for computing  $s$  and  $\pi$ :

FLOYD-WARSHALL( $d, n$ )

```

1   $s = d$ 
2  for  $i = 1$  to  $n$ 
3      for  $j = 1$  to  $n$ 
4          if  $i=j$  or  $d_{i,j}=\infty$ 
5               $\pi_{i,j} = \text{NIL}$ 
6          else  $\pi_{i,j} = i$ 
7  for  $k = 1$  to  $n$ 
8      for  $i = 1$  to  $n$ 
9          for  $j = 1$  to  $n$ 
10              $x = s_{i,k} + s_{k,j}$ 
11             if  $x < s_{i,j}$ 
12                  $s_{i,j} = x; \pi_{i,j} = \pi_{k,j}$ 

```

# Example

$$S^{(0)}/\pi^{(0)} = S^{(1)}/\pi^{(1)}$$

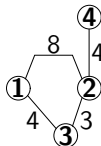
	1	2	3	4
1	0/NIL	8/1	4/1	$\infty$ /NIL
2	8/2	0/NIL	3/2	4/2
3	4/3	3/3	0/NIL	$\infty$ /NIL
4	$\infty$ /NIL	4/4	$\infty$ /NIL	0/NIL

$$S^{(2)}/\pi^{(2)}$$

	1	2	3	4
1	0/NIL	8/1	4/1	12/2
2	8/2	0/NIL	3/2	4/2
3	4/3	3/3	0/NIL	7/2
4	12/2	4/4	7/2	0/NIL

$$S^{(3)}/\pi^{(3)} = S^{(4)}/\pi^{(4)}$$

	1	2	3	4
1	0/NIL	7/3	4/1	11/2
2	7/3	0/NIL	3/2	4/2
3	4/3	3/3	0/NIL	7/2
4	11/3	4/4	7/2	0/NIL



$d$	1	2	3	4
1	0	8	4	$\infty$
2	8	0	3	4
3	4	3	0	$\infty$
4	$\infty$	4	$\infty$	0